

```

① scandir <dirent.h>
struct dirent** namelist;
int n = scandir(".", &namelist, NULL, alphasort);
if (n < 0) {
    perror("scandir"); //error
} else {
    while (n-- > 0) {
        struct dirent* d;
        d = *namelist;
        printf("%s\n", d->d_name); //reverse order
        free(d);
    }
    free(namelist);
}

```

```

② socket, connect <sys/socket.h> <sys/types.h>
struct addrinfo hints = {
    .ai_socktype = SOCK_STREAM,
    .ai_family = AF_UNSPEC,
    .ai_flags = AI_ADDRCONFIG,
};
struct addrinfo* head;
int sock;
struct addrinfo* curr;
int error = getaddrinfo("server", "port", &hints, &head);
if (error == EAI_SYSTEM) {
    die("getaddrinfo"); //error
}
for (curr = head; curr != NULL; curr = curr->ai_next) {
    sock = socket(curr->ai_family, curr->ai_socktype, curr->ai_protocol);
    if (!connect(sock, curr->ai_addr, curr->ai_addrlen)) {
        break;
    }
}
close(sock); //extl. error: -1

```

```

③ opendir, readdir <dirent.h> <sys/types.h> <sys/stat.h>
DIR* dir = opendir("."); //replace "." with your directory
if (dir == NULL) {
    die("opendir"); //error
}
struct dirent* entry;
while ((errno = 0, entry = readdir(dir)) != NULL) {
    if (strcmp(entry->d_name, ".") == 0 || strcmp(entry->d_name, "..") == 0) {
        continue; //skip . and .. works without malloc
    }
    char path[strlen(".") + strlen(entry->d_name) + 2];
    sprintf(path, "%s/%s", ".", entry->d_name);
    struct stat info;
    if (!stat(path, &info)) { //stat() does follow symlink
        continue; //error
    }
    if (!S_ISREG(info.st_mode) || !S_ISDIR(info.st_mode)) {
        continue;
    }
    printf("%s: %d bytes\n", path, info.st_size);
}
if (errno) {
    die("readdir"); //error
}
if (closedir(dir)) {
    die("closedir"); //error
}

```

```

④ pipe <unistd.h> fork, write, read
int fd[2];
char* tosend = "Hallo Welt!";
if (pipe(fd)) {
    die("pipe"); //error
}
pid_t pid = fork();
if (pid == 0) { //child
    close(fd[1]); //Ausgang nicht benötigt
    write(fd[0], tosend, strlen(tosend) + 1);
    exit(EXIT_FAILURE);
}
if (pid == -1) {
    die("fork"); //error
}
//parent
close(fd[1]); //Eingang nicht benötigt
char buf[100] = {0};
read(fd[0], buf, 99 * sizeof(char));
printf("got %s", buf);
fork(parent) -> Child PID
Child -> 0; getpid()

```

```

⑤ fopen, fgets, ferror <stdio.h>
char buf[100]; //99 + "\0"
FILE* fh = fopen("filename", "r");
if (fh == NULL) {
    die("fopen"); //error
}
//Zielformat
while (fgets(buf, 100, fh) != NULL) {
    printf("%s", buf);
}
if (ferror(fh)) {
    die("fgets"); //error
}
if (fclose(fh)) {
    die("fclose"); //error
}

```

```

⑥ sigaction, sigemptyset, sigaddset, ... <signal.h>
static void wolfgang(int sig) {
    int old = errno;
    int status;
    while (waitpid(-1, &status, WNOHANG) > 0) {
        if (WIFEXITED(status)) {
            //child terminated normally
            //collect dead children
        }
        errno = old;
    }
}
struct sigaction sa = {
    .sa_handler = wolfgang,
    .sa_flags = SA_RESTART | SA_NOCLDWAIT,
};
if (sigaction(SIGCHLD, &sa, NULL) == -1) {
    die("sigaction"); //error
}
sigset_t new, old;
sigemptyset(&new);
sigaddset(&new, SIGCHLD);
sigprocmask(SIG_BLOCK, &new, &old); //Block Signals
while (waitcond) {
    sigsuspend(&old); //Wait until signal
}
sigprocmask(SIG_SETMASK, &old, NULL); //Unblock signals

```

```

⑦ socketbind, listen, accept <sys/socket.h>
int sock = socket(AF_INET, SOCK_STREAM, 0);
if (sock == -1) {
    die("socket"); //error
}
struct sockaddr_in s;
s.sin_family = AF_INET;
s.sin_port = htons(LISTEN_PORT);
s.sin_addr = in6_addr_any;
if (-1 == bind(sock, (struct sockaddr*)&s, sizeof(s))) {
    die("bind"); //error
}
if (-1 == listen(sock, SOMAXCONN)) {
    die("listen"); //error
}
while (1) {
    int c_sock = accept(sock, NULL, NULL);
    if (c_sock == -1) {
        perror("accept"); //error
        continue;
    }
    //Code (rx, tx)
    close(c_sock);
}
close(sock);

```

```

⑧ pthread <pthread.h>
for (int i = 0; i < threadcount; i++) {
    pthread_t thread;
    if (errno = pthread_create(&thread, NULL, run, &runarg)) {
        die("pthread_create"); //error
    }
    pthread_detach(thread);
}
//alternativly:
//threads[i] = thread;
//for (int i = 0; i < threadcount; i++) {
//    pthread_join(threads[i], NULL);
//}

```

```

⑨ dup <unistd.h> //rx, tx
fopen <stdio.h>
fgets, fputs <stdio.h>
int c_txsock = dup(c_sock); //c_sock ans ④
if (c_txsock < 0) {
    die("dup");
}
FILE* rx = fopen(c_sock, "r");
if (!rx) {
    die("fopen"); //error
}
FILE* tx = fopen(c_txsock, "w");
if (!tx) {
    die("fdopen"); //error
}
if (fputs(tx, "Anfangen\n") < 0) { //senden
    die("fputs");
}
//empfangen: fgets ③ mit rx

```

```

⑩ SEMAPHORE - SEM / SEM CREATE malloc <stdlib.h>
typedef struct sem {
    volatile int count;
    pthread_mutex_t mutex;
    pthread_cond_t condition;
} SEM;
SEM* sem_create(int val) {
    SEM* new = malloc(sizeof(SEM));
    if (new == NULL) {
        return NULL; //error
    }
    new->count = val;
    if (errno = pthread_mutex_init(&new->mutex, NULL)) {
        free(new);
        return NULL; //error
    }
    if (errno = pthread_cond_init(&new->condition, NULL)) {
        pthread_mutex_destroy(&new->mutex);
        free(new);
        return NULL; //error
    }
    return new;
}

```

SERVER

SEND, RECEIVE  
SERVER

CLIENT

SIGNALS

PIPES

PTHREADS

SEMAPHORE  
CREATE

NOTE!  
No BLOCKING STUFF  
IN SIGNAL HANDLERS.  
D.H. KEIN PRINTF ETC.  
//Collect combies with DEFAULT HANDLER / IGNORE SIGNALS  
struct sigaction action = {  
 .sa\_handler = SIG\_DFL, //SIG\_IGN to ignore.  
 .sa\_flags = SA\_NOCLDWAIT | SA\_RESTART, //To ignore signal, leave empty  
};  
sigaction(SIGCHLD, &action, NULL); //error handling above

//other code:  
sigprocmask(SIG\_BLOCK, &new, &old); //Block Signals  
waitcond\_t for similar  
sigprocmask(SIG\_SETMASK, &old, NULL); //Unblock Signals

void\* run(void\* arg) {  
 pthread\_t thread;  
 if (errno = pthread\_create(&thread, NULL, run, &runarg)) {  
 die("pthread\_create"); //error  
 }  
 pthread\_detach(thread);  
}



⑩ II SEMAPHORE P() V() semDestroy()

P() - Lock

```
void P(SEM* sem) {
    pthread_mutex_lock(&sem->mutex);
    while(sem->count < 1) {
        pthread_cond_wait(&sem->condition, &sem->mutex);
        //ähnlich sigsuspend => kein. Lost wakeup.
    }
    sem->count--;
    pthread_mutex_unlock(&sem->mutex);
}
```

V() - Unlock

```
void V(SEM* sem) {
    pthread_mutex_lock(&sem->mutex);
    sem->count++;
    if(sem->count == 1) {
        pthread_cond_broadcast(&sem->condition);
    }
    pthread_mutex_unlock(&sem->mutex);
}
```

SEM-DESTROY

```
void semDestroy(SEM* sem) {
    if(sem == NULL) return; //error
    errno = pthread_cond_destroy(&sem->condition);
    if(errno) return; //error
    errno = pthread_mutex_destroy(&sem->mutex);
    if(errno) return; //error
    free(sem);
}
```

⑪ BNDBUF / CAS

```
typedef struct {
    int* values;
    size_t size;
    SEM* frei;
    SEM* belegt;
    volatile int first, last;
} BNDBUF;
```

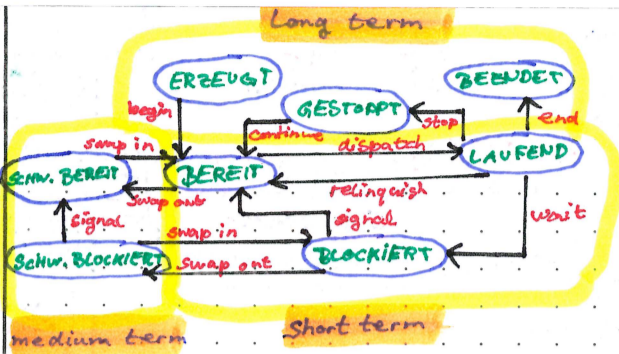
bbPut()

```
void bbPut(BNDBUF* bb, int val) {
    P(bb->frei);
    bb->values[bb->last] = val;
    bb->last = (bb->last + 1) % bb->size;
    V(bb->belegt);
}
```

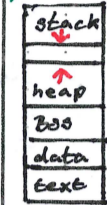
bbGet()

```
int bbGet(BNDBUF* bb) {
    int curr, next, val;
    P(bb->belegt);
    do {
        curr = bb->first;
        val = bb->values[curr];
        if(curr < bb->size - 1) {
            next = curr + 1;
        } else {
            next = 0;
        }
    } while(!__sync_bool_compare_and_swap(
        &bb->first, curr, next));
    V(bb->frei);
    return val;
}
```

- RAID 0: Speicher spiegeln aufteilen
- RAID 1: Speicher spiegeln
- RAID 4: ab 3 Platten: Platte mit XOR-Parität
- RAID 5: Wie RAID 4 mit verteiltem Paritätsblock
- RAID 6: RAID 5 mit 2 Paritätsblöcken  
↳ Ausfall von 2 Platten möglich



Adressraum



Einplanungsverfahren

- FCFS: Verarbeitung nach Ankunftszeit
- RR: regelmäßige umplanung
- VRR: RR mit variablen Zeitscheiben nach Vorzugsqueue
- SPN: Einplanung nach erwarteter Bedienzeit
- HRRN: SPN mit höherer Priorität für ältere Prozesse
- SRTF: SPN mit spontanen Umplanungen
- MLQ: Mischbetrieb, verschiedene Strategien für Prozess
- FB: regelmäßige Umplanung mit Prioritätsebenen und größeren Zeitscheiben

	FCFS	RR	VRR	SPN	HRRN	SRTF	FB
kooperativ	✓			(✓)	(✓)		
vorhängend		✓	✓			✓	✓
probabilistisch				✓	✓		
deterministisch							
Konvoi	X	X					
Verhungern	X			X			

Speicherverwaltung

- best fit: - kleinstes, passendes Loch  
- Wenig Verschchnitt  
- Langsam (Suchaufwand)
- worst fit: - größtes, passendes Loch  
- konstanter Suchaufwand  
- hinterlässt große Löcher
- first fit: - erstes, passendes Loch  
- schnell  
- kleine Löcher vorne, große hinten  
- Verschwendung, steigender Suchaufwand
- next fit: - first fit ab letztem gefüllten Loch  
- eher gleich große Löcher  
- im Mittel abnehmender Suchaufwand
- Buddy: - Halbierung

2<sup>n</sup>-Zerlegungen

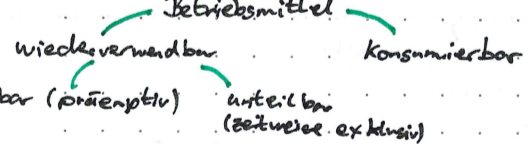
0	1	2052162	21
1	2	2104304	22
2	4	838608	23
3	8	1677216	24
4	16	3354432	25
5	32	6708864	26
6	64	13417728	27
7	128	26835456	28
8	256	53670912	29
9	512	107341824	30
10	1024		
11	2048		
12	4096		
13	8192		
14	16384		
15	32768		
16	65536		
17	131072		
18	262144		
19	524288		
20	1048576		

Verdrängungsstrategien

- MFU, LFU: unsinnig
- LRU:
  - clock: Ring Schieberegister
  - second chance: PRES-BIT
  - third chance: PRES-BIT + DIRTY-BIT

Freiseitenpuffer vor Anlagerung

- kibi 2<sup>10</sup> = 1024<sup>1</sup>
- mebi 2<sup>20</sup> = 1024<sup>2</sup>
- gebi 2<sup>30</sup> = 1024<sup>3</sup>
- tebi 2<sup>40</sup> = 1024<sup>4</sup>



Planungsstrategie:  
 kooperativ ↔ präemptiv  
 deterministisch ↔ probabilistisch  
 offline ↔ online